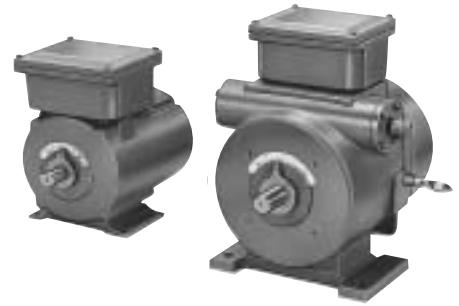


HM

High-Torque Modutrol Motor

The HM serves as an electric actuator to execute either 2-position or proportional control action, with relay contact signal input.

The housing is aluminum alloy casting making it rigid, compact and drip-proof. Internal moving parts are sealed with grease for high efficiency, low running noise and long life.



Specifications

Housing	Aluminum alloy casting					
Power	100/110Vac, 50/60Hz 200/220Vac, 50/60Hz					
Ambient temperature	0 to 60°C with 100% load factor					
Ambient humidity	Lower than 85% RH at 60°C					
Construction	Drip-proof structure					
Rotating angle	90°					
	HM-02	HM-04	HM-06	HM-10	HM-20	
Rotating time						
50Hz	30s	30s	30s	36s	36s	
60Hz	25s	25s	25s	30s	30s	
Power consumption	24VA	40VA	40VA	60VA	70VA	
Mass	5.5kg	6.5kg	7.5kg	16kg	21kg	
Accessories	One set of clamp arms (selectable) Part No. HLE02 for HM-02 Part No. HLE04 for HM-04 Part No. HLE06 for HM-06 Part No. HLE10 for HM-10 Part No. HLE20 for HM-20					

Selection Guide

I II III IV Example: HM-02-A10A

Segment	Model No. selection	Availability										Description						
		Torque (N-m)	Control outputs ON-OFF	Position proportional	Manual handle													
I	Basic No.	HM-02-A	↓										24	○	-	without		
		HM-02-B	↓										24	-	○	without		
		HM-04-A		↓									40	○	-	without		
		HM-04-B			↓								40	-	○	without		
		HM-06-A				↓							60	○	-	without		
		HM-06-B					↓						60	-	○	without		
		HM-10-A						↓					100	○	-	with		
		HM-10-B							↓				100	-	○	with		
		HM-20-A								↓			200	○	-	with		
		HM-20-B									↓		200	-	○	with		
II	Power	1	○	○	○	○	○	○	○	○	○	○	○	○	○	○	100/110Vac, 50/60Hz	
		2	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	200/220Vac, 50/60Hz
III	Option 1	0	○	-	○	-	○	-	○	-	○	-	-	-	-	-	None	
		1	-	○	-	○	-	○	-	○	-	○	-	-	-	-	○	1 feedback potentiometer
IV	Option 2	2	-	○	-	○	-	○	-	○	-	○	-	-	-	-	○	2 feedback potentiometers
		A	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	None
		B	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	2 auxiliary switches

• A circle (○) denotes availability.

ACTUATORS

Dimensions (Unit: mm)

